# AN OVERVIEW OF QUASI-RANDOM SEQUENCES / SETS

Colas Schretter Brussels Summer School of Mathematics, August 1-7, 2013



# **quasi-** (*comb. form*) seemingly; apparently but not really

EXAMPLE quasi-American | quasi-scientific ORIGIN from Latin quasi 'as if, almost.'

# **GEOMETRICAL** INTUITION



**QUESTION** Which of the two patterns is non-random and contains correlations among points?

# **GEOMETRICAL** INTUITION



**QUESTION** If you scatter black grains on a white plate, how will look the distribution of grains?

# **GEOMETRICAL** INTUITION



Random (no correlation)

Quasi-random

### VOCABULARY

MONTE CARLO • PSEUDO-RANDOM LOW-DISCREPANCY • HAMMERSLEY HALTON • VAN DER CORPUT • GRID SEQUENCE · SET · GOLDEN RATIO LATTICE • BLUE NOISE • STRATIFIED SAMPLES • NONUNIFORM SAMPLING INVERSION METHODS • THE HILBERT SPACE FILLING CURVE...

# ACKNOWLEDGMENTS

#### Collaborators

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#### Sponsors

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# COMPUTER RENDERING



Image-based lighting, 64 quasi-random samples per pixel





 $I = \iint f(x, y) \, \mathrm{d}x \, \mathrm{d}y$ 

Is analytical integration always possible?



2D function defined on D = [0,1)x [0,1)

$$I = \iint_{D} f(x, y) \, dx \, dy$$
$$\approx \frac{1}{N} \sum_{i=1}^{N} f(x_i, y_i) = \hat{I}_N$$
with  $(x_i, y_i) \in D \quad \forall i \in [1..N]$ 

Approximation with a discrete sum



$$I = \iint_{D} f(x, y) \, dx \, dy$$
$$\approx \frac{1}{N} \sum_{i=1}^{N} f(x_i, y_i) = \hat{I}_N$$
with  $(x_i, y_i) \in D \quad \forall i \in [1..N]$ 

Approximation with a discrete sum

**QUESTION** What is the expected mean integration error when the N *point samples* are chosen at random?

# RATE OF CONVERGENCE

$$\sigma^{2} = Var(f) = \iint_{D} \left[ f(x, y) - I \right]^{2} dx dy$$

# RATE OF CONVERGENCE

$$\sigma^{2} = Var(f) = \iint_{D} \left[ f(x, y) - I \right]^{2} dx dy$$
  

$$\rightarrow E \left[ \left( I - \hat{I}_{N} \right)^{2} \right] = \frac{\sigma^{2}}{N} \qquad \begin{array}{l} \text{Assume a constant mean} \\ \text{squared error (MSE) that is} \\ \text{averaged over all N samples.} \end{array}$$

constant mean

# RATE OF CONVERGENCE

$$\sigma^{2} = Var(f) = \iint_{D} [f(x, y) - I]^{2} dx dy$$
  

$$\rightarrow E\left[\left(I - \hat{I}_{N}\right)^{2}\right] = \frac{\sigma^{2}}{N} \qquad \begin{array}{l} \text{Assume a constant mean} \\ \text{squared error (MSE) that is} \\ \text{averaged over all N samples.} \end{array}$$

**Result:** The squared error between the true integral and the Monte Carlo approximation decreases linearly with the number of samples.

#### **QUESTION** Is this a *"fast"* rate of convergence?

constant mean

- We want to approximate the mean value by flipping coins and counting 0 for **heads** (H) and 100 for **tails**
- **QUESTION** How many times to you need to flip the coin to approach the mean value 50 with 1% error?

One flip	0.5
Mean:	0.45
0 or 100	0.4- 0.35-
Average error:	
(50 + 50) / 2	
= 50	0.15
	0.05
	0 0 Number of H's

Two flips Mean: 0, 50(x2) or  $100^{2} \binom{2}{k}(1/2)^{2}$ Average function of k:  $(50 + 0(x2) + 50) / 2^{2}$ = 25











Six flips Mean:

> 0, 16.6(×6), 33.3(×15), 50(×20), 66.6(×15), 83.3(×6) or 100

Average error:

(50(x2) + 33.3(x12) + 16.6(x30)) / 2<sup>6</sup>

= 15.625







= 13.671875



### AVERAGE ERROR

**QUESTION** How many times to you need to flip the coin to approach the mean value 50 with 1% error?

- I flip: avg. error = 50
- 2 flips: avg. error = 25 = 50 50 / 2
- 4 flips: avg. error = 18.75 = 25 25 / 4
- 6 flips: avg. error = 15.625 = 18.75 18.75 / 6
- 8 flips: avg. error = **I3.671875** = 15.625 15.625 / 8

**Observation:** The relative error improvement is inversely proportional to the number of sample drawn so far.

### AVERAGE ERROR

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- 8 flips: avg. error = **I3.671875** = 15.625 15.625 / 8

1592 flips: avg. error = 0.9997015 = 1.00033 - 1.00033 / 1592

## LAW OF LARGE NUMBERS



Number of coin flipping Bernoulli trials

As the number of independent *randomly* generated trials increases, their average tends to their theoretical mean.

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# LAW OF LARGE NUMBERS



Number of coin flipping Bernoulli trials

As the number of independent *randomly* generated trials increases, their average tends to their theoretical mean.

**Consequence:** If it is possible to improve the convergence rate, then there is only one way: Do not pick point samples at random!

QUASI-RANDOM POINTS

# QUASI-RANDOM POINTS



Blue noise points

Lattice rule

• • • • • •

Cartesian grid

### RANDOM SAMPLING



64 random points

1000 random points

# RANDOM SAMPLING

**Clumping**: There are regions of the integration domain that are sparsely sampled while other regions are densely covered by clusters of points.



64 random points

1000 random points

#### REGULAR **GRIDS**

•	•	•	•	•	•	•	•	•	•	٠	٠	٠	٠	٠	٠	٠	٠	٠	٠	٠	٠	٠	•
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Cartesian grid,  $8^2 = 64$  points

Cartesian grid,  $16^2 = 256$  points
# REGULAR **GRIDS**

•	•	•	Curse of dimensionality: In higher dimensions, the granularity is much coarser and it becomes very difficult to control the number of samples.															•	•	•	•	•	•
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Cartesian grid,  $8^2 = 64$  points

Cartesian grid,  $16^2 = 256$  points

### CONCAVITY -VEXITY BIAS



26 points inside a *concave* function

24 points inside a convex function

# CONCAVITY -VEXITY **BIAS**

We want to integrate the area of a half unit disc (area: Pi/2) enclosed in a unit box (area:  $2^2 = 4$ )

- Note that the ratio these two is (Pi/2)/4 = Pi/8

- When approximating the integral with  $8^2 = 64$  samples, the proportion of samples inside the shapes should be close to  $64 \times Pi/8 = 25.132$  (not 24 or 26)

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- When approximating the integral with  $8^2 = 64$  samples, the proportion of samples inside the shapes should be close to  $64 \times Pi/8 = 25.132$  (not 24 or 26)

**Bias**: When using regular grids, the integral is systematically over or under estimated for globally concave or convex functions, respectively (*Dupire & Savine*, 1998)

## STRATIFIED SAMPLES



Random samples, 64 points

Stratified samples and strata, 64 points

# STRATIFIED SAMPLES



Random samples, 64 points

Stratified samples, 64 points

## PSEUDO-RANDOM

```
unsigned int state[624];
unsigned int index;
unsigned int twist(const unsigned int u, const unsigned int v) {
    const unsigned int twisted = ((u & 0x8000000) | (v & 0x7FFFFFFF)) >> 1;
    if(v & 1) return twisted ^ 2567483615ul;
    return twisted;
}
void update() {
   index = 0;
  for(unsigned int i = 0; i < 624 - 397; ++i)</pre>
       state[i] = state[i + 397] ^ twist(state[i], state[i + 1]);
  for(unsigned int i = 624 - 397; i < 623; ++i)
       state[i] = state[i + 397 - 624] ^ twist(state[i], state[i + 1]);
  state[623] = state[396] ^ twist(state[623], state[0]);
}
unsigned int random() {
  if(index == 624) update();
  unsigned int r = state[index++];
   r ^= (r >> 11);
   r ^= (r << 7) & 2636928640ul:
   r ^= (r << 15) & 4022730752ul;
  r ^= (r >> 18);
   return r;
}
```

Mersene twister number generator (Matsumoto & Nishimura 2002)

#### "For every randomized algorithm, there is a clever deterministic one." Harald Niederreiter, 1998



LOW-DISCREPANCY POINTS

#### **dis-crep-an-cy** (*noun*) A lack of compatibility or similarity between two or more facts

ORIGIN early 17<sup>th</sup> cent.: from Latin discrepantia, from discrepare 'be discordant,' from dis- 'apart, away' + crepare 'to creak.'

#### **dis-crep-an-cy** (*noun*) A lack of <del>compatibility or</del> similarity between <del>two or more</del> facts

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#### **dis-crep-an-cy** (*noun*) A lack of <del>compatibility or</del> similarity between <del>two or more</del> <del>facts</del> points

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# DISCREPANCY CRITERIA

#### Number Theory

Box discrepancy, local discrepancy, star discrepancy, half-plane discrepancy, edge discrepancy, strip discrepancy, ...

#### Computer Graphics

Stratified samples, jittering, n-rooks, halftoning, Blue noise spectrum, Poisson disk sampling, minimum maximum distance, ...



Random (100 points)



Random (100 points)



Random (100 points)



Random (100 points)



Random (100 points)

## STAR DISCREPANCY

The discrepancy of the point set  $S = \{x_1, ..., x_N\}$  relative to a collection A of axis-aligned boxes in  $[0, 1)^d$  is

$$D^* \left( S; A \right) = \sup_{a \in A} \left| \frac{\# \left\{ x_i \in a \right\}}{N} - \operatorname{vol}(a) \right|$$

IN ONE DIMENSION

# VAN DER CORPUT SEQ.



# VAN DER CORPUT SEQ.



```
H_2(i) = {\scriptstyle \text{FUNCTION Halton(index)} \atop \ result = 0 \\ \text{f} = 1 / 2 \\ \text{i} = \text{index} \\ \text{WHILE(i > 0)} \\ \text{result += f * (i % 2)} = \\ \text{i} = \text{floor(i / 2)} \\ \text{f} = \text{f} / 2; \\ \text{END} \\ \text{RETURN result} \\ \text{END} \\ \end{array}
```

// Implementation with bitwise operations, Kollig & Keller 2002
double RI\_vdC(uint bits, uint s = 0) {
 bits = (bits << 16) | (bits >> 16);
 bits = ((bits & 0x00ff00ff) << 8) | ((bits & 0xff00ff00) >> 8);
 bits = ((bits & 0x0f0f0f0f) << 4) | ((bits & 0xf0f0f0f0) >> 4);
 bits = ((bits & 0x33333333) << 2) | ((bits & 0xccccccc) >> 2);
 bits = ((bits & 0x5555555) << 1) | ((bits & 0xaaaaaaaaa) >> 1);
 // facultative scrambling for randomization

// facultative scrambling for randomization
bits ^= s;

}

// final normalization in the range [0,1)
return (double) bits / (double) 0x10000000LL;

# GOLDEN RATIO SEQ.



# GOLDEN RATIO SEQ.



$$G_s(i) = \{s + i \cdot \phi\}, \quad \forall i \ge 1$$
$$\{x\} = x - \lfloor x \rfloor$$
$$\phi = \frac{1 + \sqrt{5}}{2} \approx 1.618034\dots$$

# GOLDEN RATIO SEQ.



$$G_s(i) = \{s + i \cdot \tau\}, \quad \forall i \ge 1$$
  
$$\{x\} = x - \lfloor x \rfloor$$
  
$$\tau = \frac{1}{\phi} = \phi - 1 = \frac{\sqrt{5} - 1}{2} \approx 0.618034\dots$$

IN TWO DIMENSIONS

# HAMMERSLEY AND HALTON



Hammersley set



Halton sequence

$$\left\{ \left(\frac{i}{N}, H_2\left(i\right)\right) \right\}_{i=1}^{N}$$

$$(H_2(i), H_3(i)), \quad \forall i \ge 1$$

# GOLDEN LATTICE RULE



Golden lattice



#### Golden sequence

$$\left\{ \left(\frac{i}{N}, G_s\left(i\right)\right) \right\}_{i=1}^{N}$$

$$(G_s(i),?), \quad \forall i \ge 1$$

# CARTESIAN/POLAR SYSTEMS



# HALTON SEQUENCE



Cartesian coordinates

Polar coordinates

# HAMMERSLEY SET



Cartesian coordinates

Polar coordinates

# **GOLDEN** LATTICE



Cartesian coordinates

Polar coordinates

# PHYLLOTAXIS INSPIRATIONS



Strawberry seeds

Flower seeds

COMPUTER RENDERING

# RAY-TRACING IN 3D SCENES





$$L_w(x,w) = \int_{\Omega} L_i(w') V(x,w') \beta_r(w,w') \cos(w,w') dw'$$
# QUASI-RANDOM SAMPLING



# AMBIENT OCCLUSION



Random (16 spp)

Random (64 spp)

# AMBIENT OCCLUSION



Golden lattice (16 spp)

Golden lattice (64 spp)

## HDR LIGHT PROBE



Pisa light probe, courtesy of Paul Debevec

## **IMAGE-BASED** LIGHTING



Golden lattice (64 spp)

Golden lattice (256 spp)

NON-UNIFORM SAMPLING

## PROBABILITY **DENSITY**

Piecewise-linear ramp gradient

## WARPED POINT SET

Warped Hammersley set (256 points)

### WARPED POINT SET

Warped golden lattice (256 points)

## PROBABILITY **DENSITY**

Mixture of two multivariate Gaussians

#### WARPED POINT SET

Warped Hammersley set (256 points)

## WARPED POINT SET

Warped golden lattice (256 points)

## HDR LIGHT PROBE



Pisa light probe, courtesy of Paul Debevec

## WARPED POINT SET



Warped Hammersley set (256 points)

## WARPED POINT SET



Warped golden lattice (256 points)

# PREBELEMSDATEPERMENT

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#### Input: density image

Output: point sequence

# THE INVERSION METHOD



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# THE INVERSION METHOD

Given the cumulative density function **F** from the probability density function (PDF) **f** 

- I. Generate a uniform *random* number **u** in the interval **[0,1**)
- 2. With numerical integration, compute x such that F(x) = u
- 3. Take **x** to be a non-uniform *random* number drawn from **f**



Illustration from D. Kelton, 2002

# THE INVERSION METHOD

Given the cumulative density function **F** from the probability density function (PDF) **f** 

- I. Generate a uniform *random* number **u** in the interval **[0,1**)
- 2. With numerical integration, compute  $\mathbf{x}$  such that  $\mathbf{F}(\mathbf{x}) = \mathbf{u}$
- 3. Take **x** to be a non-uniform *random* number drawn from **f**



Illustration from D. Kelton, 2002

2D INVERSION METHODS

# A- DUAL STEPS METHOD

Generate a low-discrepancy 2D point sequence, e.g. the Halton sequence.

Then, transform the first coordinate with a marginal distribution function and the inversion method.

Then, transform the second coordinate with the corresponding conditional distribution function.

(Devroye, p. 96, 1986)

# B- SINGLE STEP METHOD

Generate a suitable low-discrepancy ID sequence, e.g. the Golden ratio sequence.

Then, transform the ID coordinate along a suitable unfolded image, with the inversion method.

Then, map the coordinate to a higher-dimensional point with the inverse Hilbert space filling curve.

(Schretter and Niederreiter, 2012)

# SPACE FILLING CURVE



I<sup>st</sup> order Hilbert SFC 2<sup>nd</sup> order Hilbert SFC 3<sup>rd</sup> order Hilbert SFC

The position of the hollow point corresponds to the middle position along the path of the Hilbert SFC.

Arbitrary spatial precision can be reached with a sufficient order of recursion (order 24 for IEEE floats).



# A- DUAL STEPS METHOD



Halton sequence



Density image





ID marginal (y) and conditional (x) PDFs



ID marginal (x) and conditional (y) PDFs

# B- SINGLE STEP METHOD



#### INVERSION **Results**



#### Dual inversion, 65536 points

Single inversion, 65536 points

#### INVERSION **Results**



Dual inversion, 65536 points

Single inversion, 65536 points

100

## INVERSION **Results**

Artifacts: Sudden variations among conditional density functions profiles result in visible structures (artifacts) after dual steps inversion.



Single inversion, 65536 points

## UNIFORM DENSITY



Halton sequence

Golden sequence + Hilbert mapping

# UNIFORM DENSITY



Halton sequence

Golden sequence + Hilbert mapping







THE FINAL WORDS



## CONCLUSION


## SUGGESTED **BOOKS**

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## Random Number Generation and Quasi-Monte Carlo Methods

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## **THANK YOU** FOR NOT USING random()

Colas Schretter

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